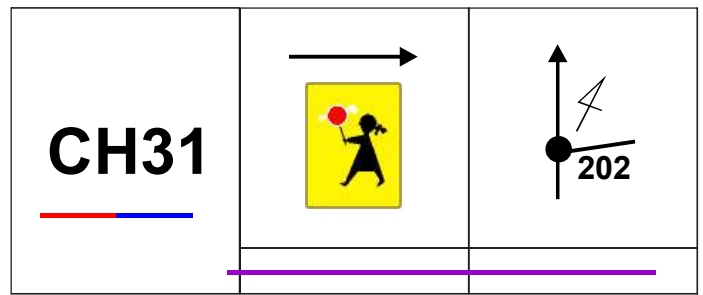
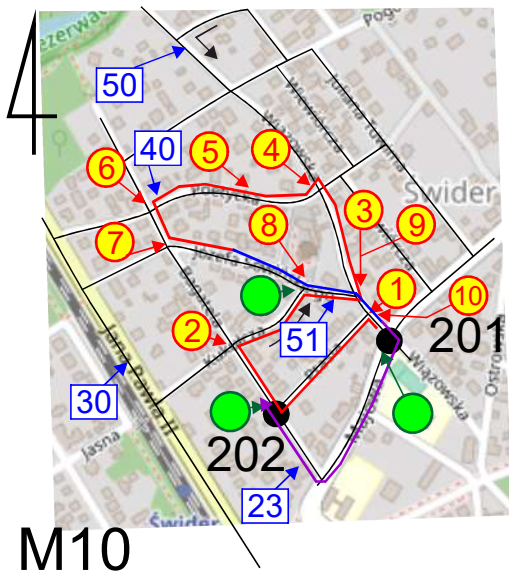
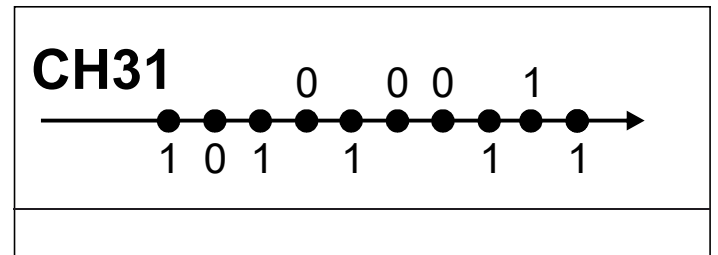


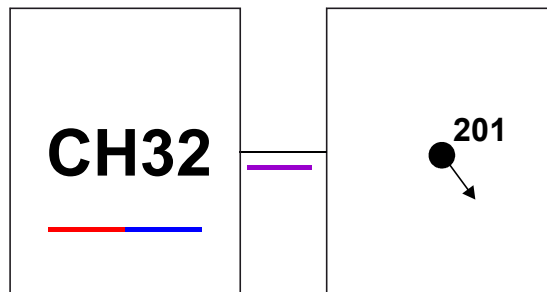
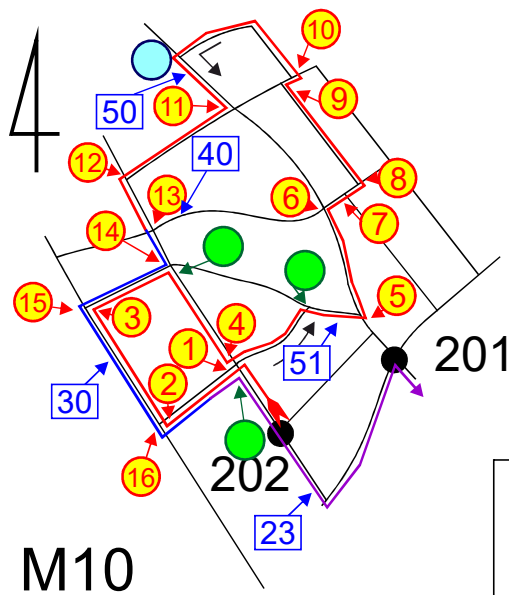
PLAN C



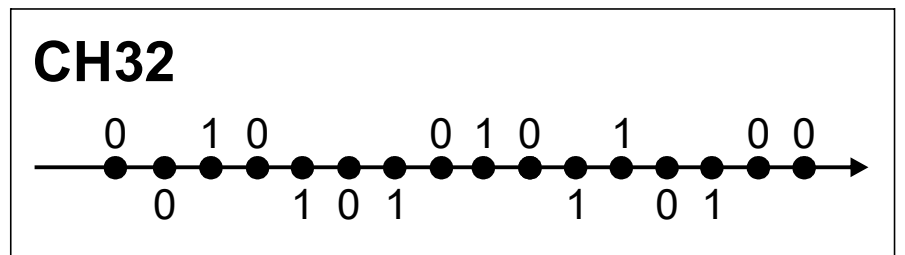
- 1 kolejne manewry choinki
- constans realny



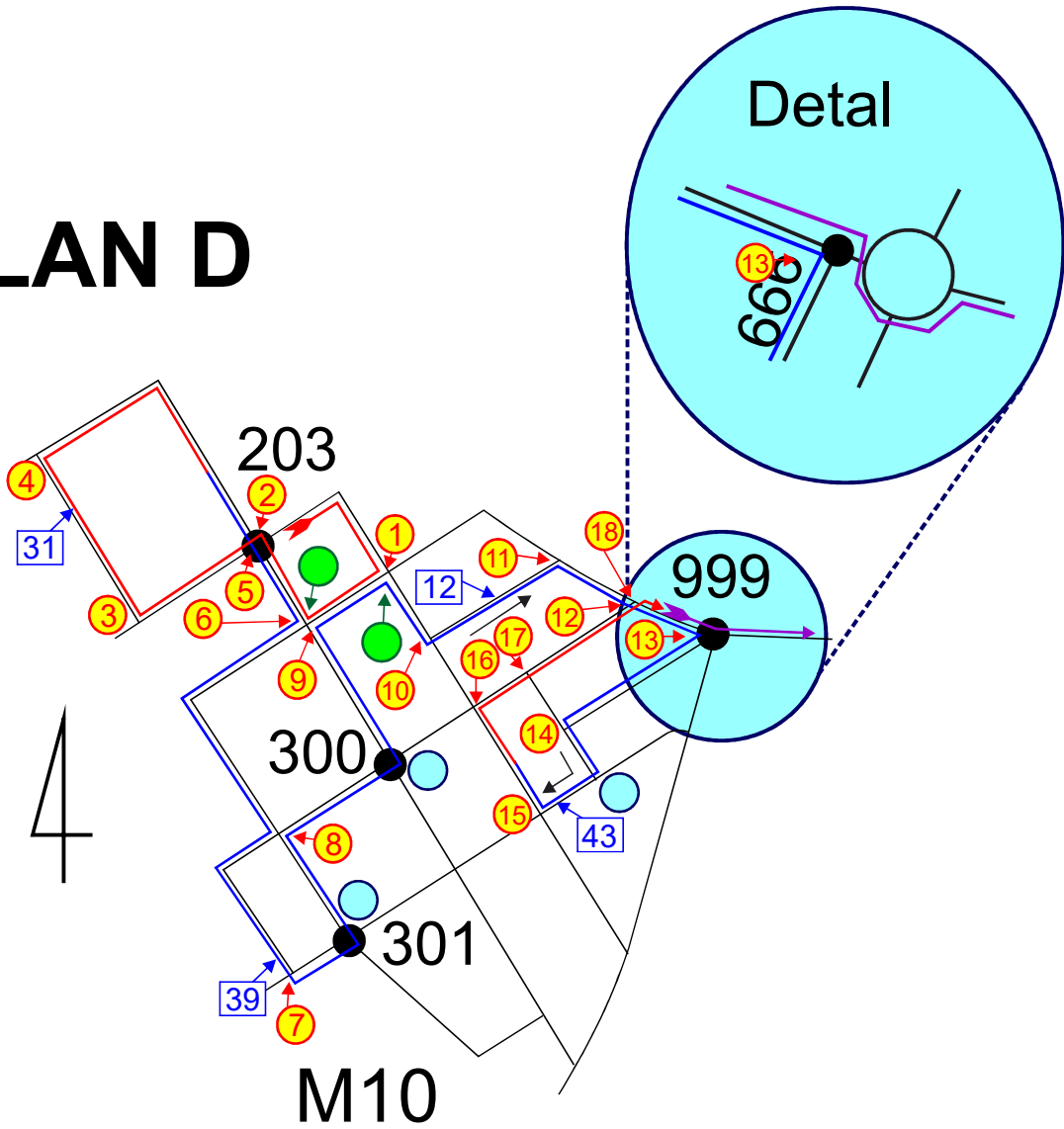
PLAN C



- jednoznaczny przejazd mapowy
- 1 kolejne manewry choinki
- constans realny



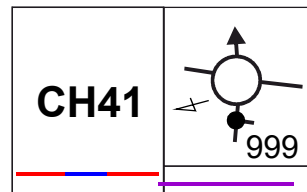
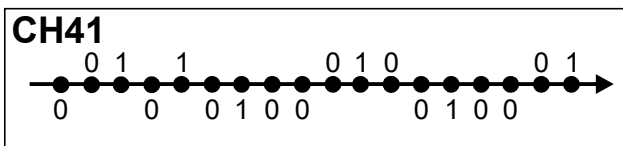
PLAN D



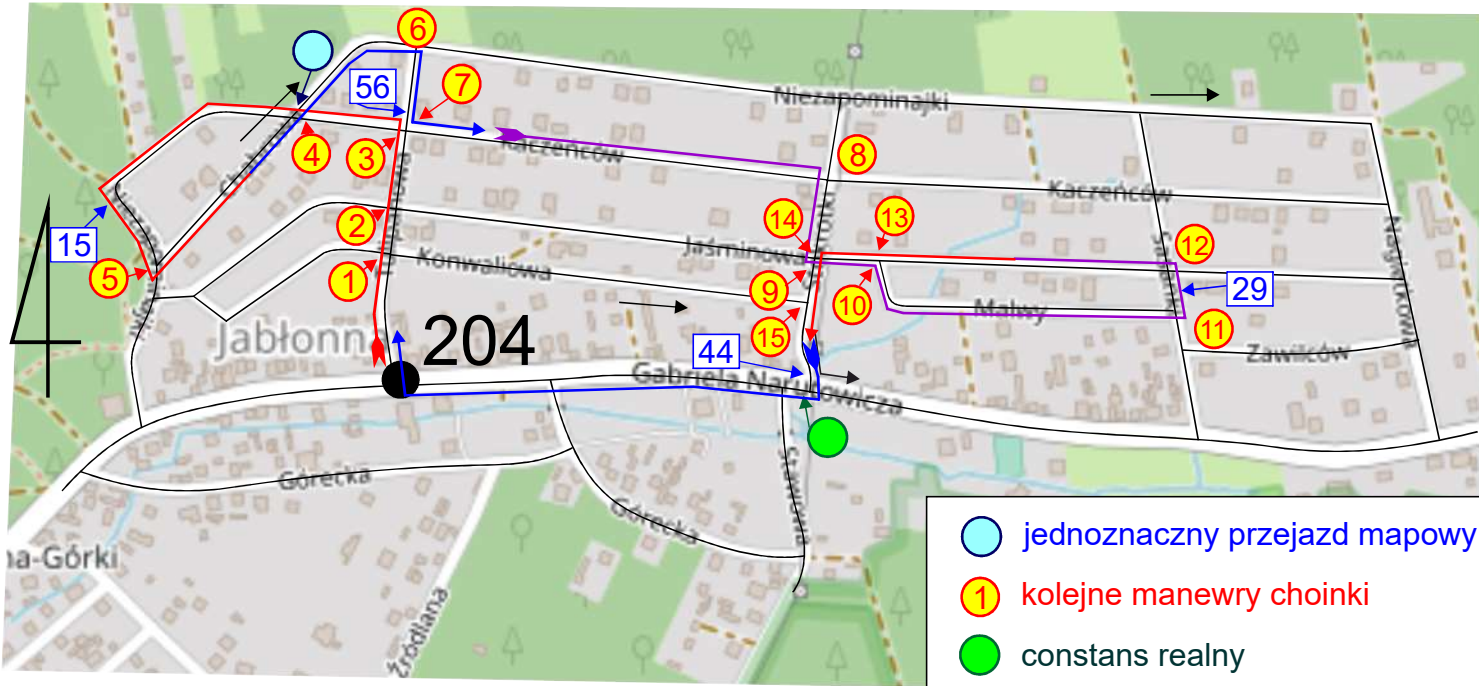
- jednoznaczny przejazd mapy
- ① kolejne manewry choinki
- constans realny

Constans

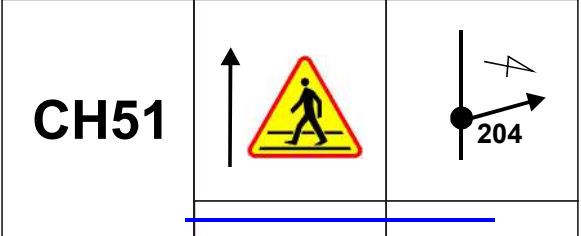
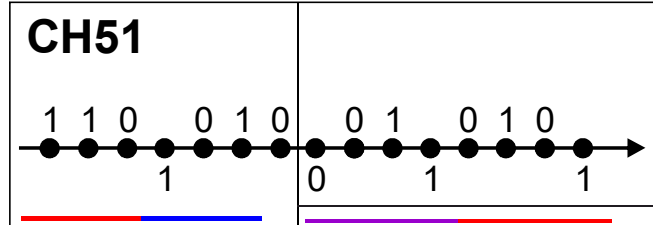
$x = 0, 1..9$
 $y = 0, 1..9$



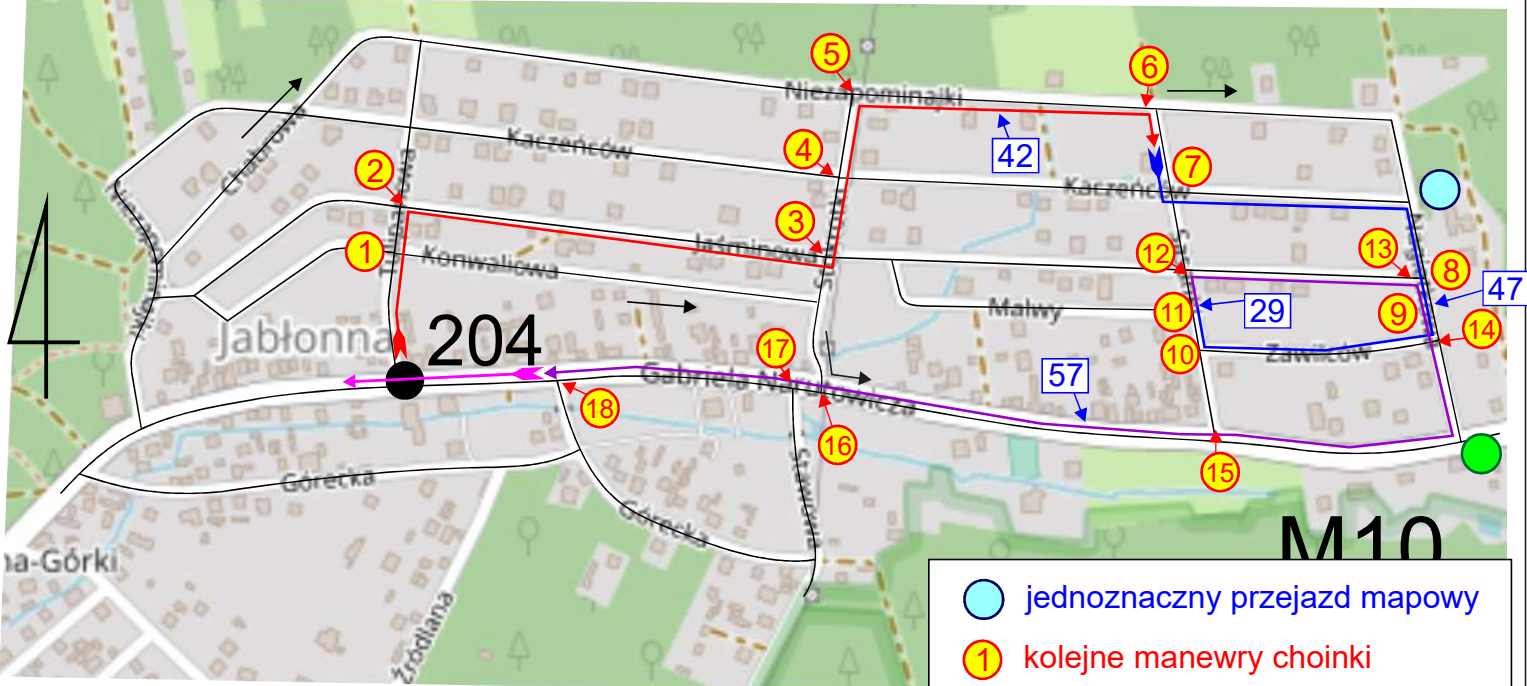
PLAN E



- jednoznaczny przejazd mapowy
- ① kolejne manewry choinki
- constans realny



PLAN E



- jednoznaczny przejazd mapowy
- ① kolejne manewry choinki
- constans realny

